

Differential algebras of quasi-Jacobi forms of index 0

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1. Introduction : derivations of modular forms

1.1. Modular forms. References: [Ser78]

We recall that a modular form of weight $k \in \mathbb{Z}_{\geq 0}$ on $SL(2, \mathbb{Z})$ is the vector space \mathcal{M}_k of holomorphic functions f on $\mathcal{H} = \{z \in \mathbb{C} : \text{Im } z > 0\}$ that satisfies

$$\forall \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL(2, \mathbb{Z}) \quad \forall \tau \in \mathcal{H} \quad \underbrace{(c\tau + d)^{-k} f\left(\frac{a\tau + b}{c\tau + d}\right)}_{=: f|_k \begin{pmatrix} a & b \\ c & d \end{pmatrix}(\tau)} = f(\tau)$$

and

$$f(\tau) = \sum_{n=0}^{+\infty} \widehat{f(n)} e(n\tau) \quad e(\xi) = \exp(2\pi i \xi).$$

The algebra \mathcal{M} of all modular forms is a polynomial algebra

$$\mathcal{M} = \bigoplus_{\substack{k \in 2\mathbb{Z}_{\geq 0} \\ k \neq 2}} \mathcal{M}_k = \mathcal{M} = \mathbb{C}[e_4, e_6]$$

where

$$\forall k \in 2\mathbb{Z}_{\geq 0} \quad k \geq 4 \quad e_k(\tau) = \sum_{\omega \in \mathbb{Z} \oplus \tau\mathbb{Z}} \frac{1}{\omega^k}. \quad (1.1)$$

The algebra \mathcal{M} is not stable by differentiation with respect to τ .

1.2. Serre's derivative. References: [Zag08]

Let

$$\partial_\tau = \frac{\pi}{2i} \frac{\partial}{\partial \tau}.$$

We define the linear map

$$Se_k : f \mapsto 4 \partial_\tau(f) - kf e_2$$

and prove that it satisfies $Se_k(\mathcal{M}_k) = \mathcal{M}_{k+2}$. This is the restriction to \mathcal{M}_k of a derivation Se of the algebra \mathcal{M} .

The introduction of Serre's derivative is a response to the lack of stability under differentiation in the algebra of modular forms.

1.3. Quasimodular forms. References: [Roy12]

Differentiating the definition of modular forms leads to

$$(c\tau + d)^{-k-2n} \frac{\partial^n f}{\partial \tau^n} \left(\frac{a\tau + b}{c\tau + d} \right) = \sum_{r=0}^n f_r(\tau) \left(\frac{c}{c\tau + d} \right)^r$$

for some (explicitly computable) holomorphic functions f_r not depending on $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$. This computation justifies the following definition implying the cocycle:

$$\begin{aligned} X &: \mathrm{SL}(2, \mathbb{Z}) \rightarrow \mathbb{C}^{\mathcal{H}} \\ \begin{pmatrix} a & b \\ c & d \end{pmatrix} &\mapsto \left(\tau \mapsto \frac{c}{c\tau + d} \right). \end{aligned}$$

Definition 1.1. A holomorphic function $f \in \mathbb{C}^{\mathcal{H}}$ is a quasimodular form of weight k and depth s if there exist holomorphic functions f_0, \dots, f_s with $f_s \neq 0$ such that

$$\forall \gamma \in \mathrm{SL}(2, \mathbb{Z}) \quad f|_k \gamma = \sum_{r=0}^s f_r X(\gamma)^r$$

and

$$\forall r \quad f_r(\tau) = \sum_{n=0}^{+\infty} \widehat{f}_r(n) e(n\tau).$$

Since

$$\frac{\partial X^2}{\partial \tau} = -X^2,$$

the definition of quasimodular forms implies that $\mathcal{M}^{\leq \infty}$ is stable by differentiation.

The derivatives of modular forms describe nearly all quasimodular forms. The vector space of quasimodular forms of weight k is

$$\mathcal{M}_k^{\leq \infty} = \bigoplus_{r=0}^{k/2-2} \frac{\partial^r}{\partial \tau^r} \mathcal{M}_{k-2r} \oplus \mathbb{C} \frac{\partial^{k/2-1}}{\partial \tau^{k/2-1}} e_2$$

where e_2 is defined similarly to (1.1) but with extra care due to the lack of absolute convergence:

$$e_2(\tau) = \lim_{N \rightarrow +\infty} \sum_{n=-N}^N \lim_{M \rightarrow +\infty} \sum_{\substack{m=-M \\ (m,n) \neq (0,0)}}^M \frac{1}{(m\tau + n)^2}.$$

The algebra of quasimodular forms is also a polynomial algebra

$$\mathcal{M}^{\leq \infty} = \mathcal{M}[e_2] = \mathbb{C}[e_2, e_4, e_6].$$

The introduction of the notion of quasi-modular forms is a response to the lack of stability under differentiation in the algebra of modular forms.

1.4. Rankin-Cohen brackets. References: [CS17]

Another notion provides us with a response, that has been initiated by Rankin and fully developed by Henri Cohen. The typical question is to find a bilinear form in the derivatives of two modular forms in such a way to obtain a new modular form. A prototypical example is the following: if $f \in \mathcal{M}_k$ and $g \in \mathcal{M}_\ell$, then

$$[f, g]_1 = kf \partial_\tau(g) - \ell g \partial_\tau(f) \in \mathcal{M}_{k+\ell+2}.$$

Cohen extended this showing that

$$[f, g]_n = \sum_{r=0}^n (-1)^r \binom{k+n-1}{n-r} \binom{\ell+n-1}{r} \partial_\tau^r(f) \partial_\tau^{n-r}(g) \in \mathcal{M}_{k+\ell+2n}$$

for any n . Note that $[,]_n$ can be extended to \mathcal{M} by bilinear extension.

A fact conjectured by Eholzer and proved by the combination of efforts of Cohen, Manin & Zagier on the one hand and Yao on the other hand is that the family $([,]_n)_{n \in \mathbb{Z}_{\geq 0}}$ is a *formal deformation*.

Definition 1.2. Let A be a commutative \mathbb{C} -algebra and $(\mu_j)_{j \in \mathbb{Z}_{\geq 0}}$ a family of bilinear maps from $A \times A$ to A such that μ_0 is the product on A . Let $A[[\hbar]]$ be the commutative algebra of formal power series in \hbar with coefficients in A . Then, $(\mu_j)_{j \in \mathbb{Z}_{\geq 0}}$ is a formal deformation of A if the non-commutative product on $A[[\hbar]]$ defined by extension of

$$f * g = \sum_{j \in \mathbb{Z}_{\geq 0}} \mu_j(f, g) \hbar^j \quad (f, g \in A)$$

is associative.

This notion encodes a wide range of equalities since, the associativity of $*$ is equivalent to

$$\sum_{r=0}^n \mu_{n-r}(\mu_r(f, g), h) = \sum_{r=0}^n \mu_{n-r}(f, \mu_r(g, h)) \quad (f, g, h \in A).$$

The introduction of the notion of formal deformation is a response to the lack of stability under differentiation in the algebra of modular forms.

2. Derivations of Jacobi forms

2.1. **Jacobi forms.** *References:* [EZ85, DMR24]

The notion of modular form originates in the action of $SL(2, \mathbb{Z})$ to \mathcal{H} and the notion of weight is attached to the cocycle

$$j : SL(2, \mathbb{Z}) \rightarrow \mathbb{C}^{\mathcal{H}}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \mapsto \left(\tau \mapsto \frac{c}{c\tau + d} \right).$$

This is a cocycle of $SL(2, \mathbb{Z})$ for its action of weight 1 on \mathcal{H} , meaning

$$j(\gamma\gamma')(\tau) = j(\gamma)(\gamma'\tau)j(\gamma')(\tau).$$

The multiplicative groupe $SL(2, \mathbb{Z})$ acts on the additive group \mathbb{Z}^2 (whose elements are identified with 1×2 matrices) by right multiplication

$$((\lambda, \mu), \begin{pmatrix} a & b \\ c & d \end{pmatrix}) \mapsto (\lambda\mu) \begin{pmatrix} a & b \\ c & d \end{pmatrix} = (\lambda a + \mu c, \lambda b + \mu d)$$

and on $\mathcal{H} \times \mathbb{C}$ by

$$\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\tau, z) \right) \mapsto \left(\frac{a\tau + b}{c\tau + d}, \frac{z}{c\tau + d} \right)$$

whereas \mathbb{Z}^2 acts on $\mathcal{H} \times \mathbb{C}$

$$(\lambda, \mu)(\tau, z) \mapsto (\tau, z + \lambda\tau + \mu).$$

The semi-direct product $SL(2, \mathbb{Z}) \ltimes \mathbb{Z}^2$ is the set $SL(2, \mathbb{Z}) \times \mathbb{Z}^2$ with the group operation

$$(\gamma, x) \cdot (\gamma', x') = (\gamma\gamma', x\gamma' + x').$$

It acts on $\mathcal{H} \times \mathbb{C}$ the following way:

$$\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\lambda, \mu) \right) \mapsto \begin{pmatrix} a & b \\ c & d \end{pmatrix} ((\lambda, \mu)(\tau, z)) = \left(\frac{a\tau + b}{c\tau + d}, \frac{z + \lambda\tau + \mu}{c\tau + d} \right).$$

Let G be a group acting on the right on the group H via \circ . This action defines a morphism from G into $\text{Aut}(H)$: $g \mapsto (h \mapsto h \circ g)$, and thus a group $G \ltimes H$, called the semidirect product of G and H , whose product is given by

$$(g, h) \ltimes (g', h') = (gg', (h \circ g')h').$$

Let F be a set on which G acts on the left via $|_G$, and H acts on the left via $|_H$. Assume that the actions are compatible in the following sense:

$$\forall (g, h) \in G \times H \quad \forall f \in F \quad g|_G((h \circ g)|_H f) = h|_H(g|_G f).$$

Then, a left action of $G \ltimes H$ on F is defined by setting

$$\forall (g, h) \in G \times H \quad \forall f \in F \quad (g, h)|f = g|_G(h|_H f).$$

We have two cocycles of $\text{SL}(2, \mathbb{Z})$ into $\mathbb{C}^{\mathcal{H} \times \mathbb{C}}$ described by

$$j\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right)(\tau, z) = c\tau + d \quad \ell\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right)(\tau, z) = e\left(-\frac{cz^2}{c\tau + d}\right)$$

and one of \mathbb{Z}^2 into $\mathbb{C}^{\mathcal{H} \times \mathbb{C}}$ described by

$$\rho(\lambda, \mu)(\tau, z) = e(\lambda^2\tau + 2\lambda z).$$

$$\rho((\lambda, \mu) + (\lambda', \mu'))(\tau, z) = \rho((\lambda, \mu))(\tau, z) \cdot \rho((\lambda', \mu'))(\tau, z)$$

By a general method, one deduces a cocycle of $\text{SL}(2, \mathbb{Z}) \ltimes \mathbb{Z}^2$ into $\mathbb{C}^{\mathcal{H} \times \mathbb{C}}$ described by

$$\nu\left(\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\lambda, \mu)\right)\right)(\tau, z) = (c\tau + d)^{-k} \underbrace{e^m}_{\exp(2\pi i m \cdot)} \left(-\frac{c(z + \lambda\tau + \mu)^2}{c\tau + d} + \lambda^2\tau + 2\lambda z\right).$$

Let G and H be two groups written multiplicatively.

Assume that G acts on the right on H .

Let A be an abelian group on which G acts on the right via $|_G$ and H acts on the right via $|_H$, with the actions of G and H on A respecting the group structures.

Assume that the actions are compatible in the following sense:

$$\forall (g, h) \in G \times H \quad \forall a \in A \quad (a|_G g)|_H(hg) = (a|_H h)|_G g.$$

Let ν_G be a cocycle of G in A , and let ν_H be a cocycle of H in A . Define

$$\nu : G \times H \rightarrow A \\ (g, h) \mapsto (\nu_G(g)|_H h) \cdot \nu_H(h).$$

The map is a cocycle of $G \ltimes H$ in A if and only if it satisfies the cocycle condition on $(e_G, H) \ltimes (G, e_H)$, that is, if and only if

$$\forall (g, h) \in G \times H \quad \frac{\nu_G(g)|_H(hg)}{\nu_G(g)} = \frac{\nu_H(h)|_G g}{\nu_H(hg)}.$$

Finally, we have an action of $SL(2, \mathbb{Z}) \ltimes \mathbb{Z}^2$ on $\mathbb{C}^{\mathcal{H} \times \mathbb{C}}$, of weight k and depth m described by

$$f|_{k,m} \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\lambda, \mu) \right) (\tau, z) = (c\tau + d)^{-k} e^m \left(-\frac{c(z + \lambda\tau + \mu)^2}{c\tau + d} + \lambda^2\tau + 2\lambda z \right) f \left(\frac{a\tau + b}{c\tau + d}, \frac{z + \lambda\tau + \mu}{c\tau + d} \right).$$

Note that if f is invariant under this action, then it is 1-periodic both in the τ and z aspects. In particular, if it has a Laurent expansion around 0 given by

$$f(\tau, z) = \sum_{n=-N}^{+\infty} A_n(\tau) z^n$$

then, the Laurent coefficients are 1-periodic in the τ aspect.

The notion of singularity entails the analytic conditions we shall add to the invariant functions under the action of $SL(2, \mathbb{Z}) \ltimes \mathbb{Z}^2$. A function $f \in \mathbb{C}^{\mathcal{H} \times \mathbb{C}}$ is *singular* if

- For any τ , the function $z \mapsto f(\tau, z)$ is 1-periodic, meromorphic with poles in $\mathbb{Z} \oplus \tau\mathbb{Z}$, all having same order not depending on τ ,
- The function $\tau \mapsto f(\tau, z)$ is 1-periodic
- The Laurent coefficients A_n are holomorphic on \mathcal{H} and have a Fourier expansion of the form

$$A_n(\tau) = \sum_{r=0}^{+\infty} \widehat{A}_n(r) e(r\tau).$$

A *singular Jacobi form* of weight k and index m is then a function $f \in \mathbb{C}^{\mathcal{H} \times \mathbb{C}}$ that is invariant under the action of $SL(2, \mathbb{Z}) \ltimes \mathbb{Z}^2$ of weight k and index m and singular.

We focus on the case $m = 0$ and shall omit to say "of index 0" at any time we should. We denote by \mathcal{J} the algebra of all singular Jacobi forms of index 0. Examples are

- (1) Any modular form,

(2) The Weierstrass function

$$\wp(\tau, z) = \frac{1}{z^2} + \sum_{\substack{\omega \in \mathbb{Z} \oplus \tau\mathbb{Z} \\ \omega \neq 0}} \frac{1}{(z - \omega)^2} - \frac{1}{\omega^2}$$

that satisfies

$$\wp(\tau, z) = \frac{1}{z^2} + \sum_{n=1}^{+\infty} (2n+1) e_{2n+2}(\tau) z^{2n}$$

is a singular Jacobi form of weight 2 and index 0,

(3) its derivatives with respect to the second variable

$$\underbrace{\partial_z \wp}_{\partial/\partial z}$$

is a singular Jacobi form of weight 3 and index 0.

Proposition 2.1 (van Ittersum ; Dumas, Martin & Royer). *The three singular Jacobi forms \wp , $\partial_z \wp$ and e_4 are algebraically independent and generate the algebra of singular Jacobi forms:*

$$\mathcal{J} = \mathbb{C}[\wp, \partial_z \wp, e_4].$$

$$e_6 = -\frac{1}{140}(\partial_z \wp)^2 + \frac{1}{35}\wp^3 - \frac{3}{7}\wp e_4.$$

2.2. Oberdieck's derivative. *References:* [Obe14, CDMR21a]

If \mathcal{J} is trivially stable by ∂_z , it can be seen that it is not stable by ∂_τ , for example by remarking that $\partial_\tau e_4$ is not a modular form. Oberdieck's derivative plays for \mathcal{J} the role that Serre's derivative plays for modular forms.

Let E_1 be defined by

$$\begin{aligned} E_1(\tau, z) &= \lim_{N \rightarrow +\infty} \sum_{n=-N}^N \lim_{M \rightarrow +\infty} \sum_{\substack{m=-M \\ (m,n) \neq (0,0)}}^M \frac{1}{z + m\tau + n} \\ &= \frac{1}{z} - \sum_{r=0}^{+\infty} e_{2r+2}(\tau) z^{2r+1}. \end{aligned}$$

Oberdieck's derivation is defined by over \mathcal{J}_k by

$$\text{Ob}_k(f) = \underbrace{4 \partial_\tau(f) - k e_2 f}_{S e_k(f)} + E_1 \partial_z(f) \quad (f \in \mathcal{J}_k)$$

and its linear extension Ob to \mathcal{J} satisfies (Oberdiecks : Choie, Dumas, Martin & Royer) $\text{Ob}(\mathcal{J}) \subset \mathcal{J}$, and more precisely $\text{Ob}(\mathcal{J}_k) \subset \mathcal{J}_{k+2}$.

By dimension consideration, $\text{Ob}(\wp)$ belongs to the space \mathcal{J}_4 generated by \wp and e_4 . One deduces that $\text{Ob}(\wp) = -2(\wp^2 - 10 e_4)$ which leads to the well known

$$2(2n+1) \partial_\tau e_{2n+2} = (n+1)(2n+1) e_{2n+2} e_2 - (n+2)(2n+5) e_{2n+4} + \sum_{\substack{a \geq 1, b \geq 1 \\ a+b=n}} (2a+1)(a-2b-1) e_{2a+2} e_{2b+2}.$$

2.3. Quasi-Jacobi forms. References: [v123, DMR24]

The action of $\text{SL}(2, \mathbb{Z}) \ltimes \mathbb{Z}^2$ on $\mathcal{H} \times \mathbb{C}$ is described by

$$\begin{aligned} \text{H} : \text{SL}(2, \mathbb{Z}) \ltimes \mathbb{Z}^2 &\rightarrow (\mathcal{H} \times \mathbb{C})^{\mathcal{H} \times \mathbb{C}} \\ \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\lambda, \mu) \right) &\rightarrow \begin{matrix} \mathcal{H} \times \mathbb{C} & \rightarrow & \mathcal{H} \times \mathbb{C} \\ (\tau, z) & \mapsto & \left(\frac{a\tau+b}{c\tau+d}, \frac{z+\lambda\tau+\mu}{c\tau+d} \right). \end{matrix} \end{aligned}$$

that satisfies

$$\frac{\partial \text{H}}{\partial \tau} = \left(\frac{1}{j^2}, -\frac{Y}{j} \right) \quad \frac{\partial \text{H}}{\partial z} = \left(0, \frac{1}{j} \right)$$

where Y is defined by:

$$Y\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\lambda, \mu)\right)(\tau, z) = \frac{cz + c\mu - d\lambda}{c\tau + d}.$$

Moreover (X is the natural extension to $\text{SL}(2, \mathbb{Z}) \ltimes \mathbb{Z}^2$ of the previously defined X function)

$$\frac{\partial j}{\partial \tau} = Xj \quad \frac{\partial j}{\partial z} = 0 \quad \frac{\partial Y}{\partial \tau} = -XY \quad \frac{\partial Y}{\partial z} = X \quad \frac{\partial X}{\partial \tau} = -X^2 \quad \frac{\partial X}{\partial z} = 0.$$

This remark justifies, since our goal is the stability by ∂_τ and ∂_z to introduce the following notion of quasi-Jacobi form.

Definition 2.2. A singular function $f \in \mathbb{C}^{\mathcal{H} \times \mathbb{C}}$ is a quasi-Jacobi form of weight k and depth (s_1, s_2) if there exist singular functions $(f_{r_1, r_2})_{\substack{0 \leq r_1 \leq s_1 \\ 0 \leq r_2 \leq s_2}}$ with $f_{s_1, s_2} \neq 0$ such that

$$\forall A \in \mathrm{SL}(2, \mathbb{Z}) \ltimes \mathbb{Z}^2 \quad f|_{k,0} A = \sum_{r_1=0}^{s_1} \sum_{r_2=0}^{s_2} f_{r_1, r_2} X(A)^{r_1} Y(A)^{r_2}.$$

The corresponding notation are $\mathcal{J}_k^{\leq s_1, s_2}$ for the vector space of quasi-Jacobi forms of weight k and depth (u, v) with $u \leq s_1$ and $v \leq s_2$ and $\mathcal{J}^{\leq \infty}$ for the algebra of all the quasi-Jacobi forms.

This algebra is stable by the derivations with respect to both variables:

$$\partial_\tau \left(\mathcal{J}_k^{\leq s_1, s_2} \right) \subset \mathcal{J}_{k+2}^{\leq s_1+1, s_2+1} \quad \text{and} \quad \partial_z \left(\mathcal{J}_k^{\leq s_1, s_2} \right) \subset \mathcal{J}_{k+1}^{\leq s_1+1, s_2}.$$

A prototypical example, beside all quasimodular forms and all Jacobi forms is E_1 since

$$E_1|_{1,1} A = E_1 + 2\pi i Y(A)$$

and hence $E_1|_1$ has weight 1 and depth $(0, 1)$. Together with e_2 whose depth is $(1, 0)$, one can recursively decrease the depth of any quasi-jacobi form and prove

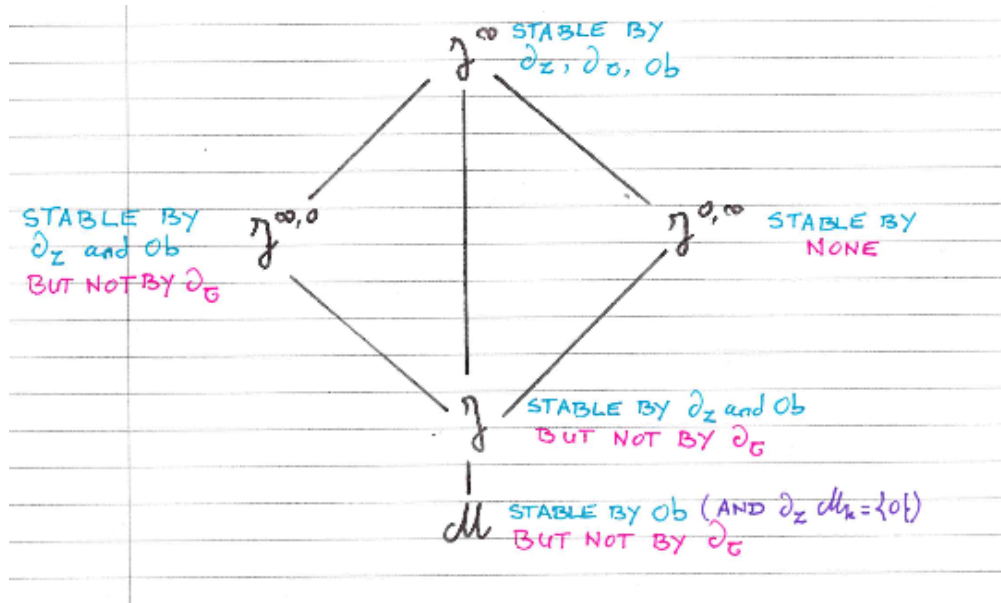
$$\mathcal{J}^{\leq \infty} = \mathcal{J}[E_1, e_2] = \mathbb{C}[\wp, \partial_z \wp, e_4, E_1, e_2].$$

From the notion of a *bi*-depth emerge two remarkable subalgebras of quasi-Jacobi forms:

$$\mathcal{J}^{\leq \infty, 0} = \mathbb{C}[\wp, \partial_z \wp, e_4, e_2] \quad (\text{quasimodular type})$$

and

$$\mathcal{J}^{\leq 0, \infty} = \mathbb{C}[\wp, \partial_z \wp, e_4, E_1] \quad (\text{elliptic type}).$$



2.4. **Bilinear combinations of derivatives.** Reference: [DMR24]

2.4.1. Rankin-Cohen brackets of elliptic type. Since $\mathcal{J}^{\leq \infty}$ is stable by ∂_τ , then

$$[f, g]_n = \sum_{r=0}^n (-1)^r \binom{k+n-1}{n-r} \binom{l+n-1}{r} \partial_\tau^r(f) \partial_\tau^{n-r}(g)$$

(with $f \in \mathcal{J}_k^{\leq \infty}$ and $g \in \mathcal{J}_l^{\leq \infty}$) extends to a sequence of bilinear maps from $\mathcal{J}^{\leq \infty} \times \mathcal{J}^{\leq \infty}$ to $\mathcal{J}^{\leq \infty}$, and indeed this remains true if we replace the binomial coefficients by any other coefficients... However, the particular choice we made for the coefficients implies that $([,]_n)_{n \in \mathbb{Z}_{\geq 0}}$ is a *formal deformation* of $\mathcal{J}^{\leq \infty}$. This results from a general result we established with Choie, Dumas & Martin in 2021 [CDMR21b] and whose proof relies on a 2004 result due to Connes & Moscovici [CM04].

Let $A = \bigoplus_{k \in \mathbb{Z}_{\geq 0}} A_k$ be a graded commutative \mathbb{C} -algebra, and D a derivation of A such that $D(A_k) \subset A_{k+2}$ for any $k \geq 0$. Let us consider the sequence $([,]_n^D)_{n \geq 0}$ of bilinear maps $A \times A \rightarrow A$ defined by bilinear extension of

$$[f, g]_n^D = \sum_{r=0}^n (-1)^r \binom{k+n-1}{n-r} \binom{l+n-1}{r} D^r(f) D^{n-r}(g),$$

for any $f \in A_k, g \in A_l$. Then, $([,]_n^D)_{n \geq 0}$ is a formal deformation of A .

A bit more surprising is the fact that $\mathcal{J}^{\leq \infty} 0, \infty$ is also stable by $([\cdot, \cdot]_n)_{n \in \mathbb{Z}_{\geq 0}}$. To prove this result, we developpe,d,a gain with Choie, Dumaus & Martin a general method called *extension-restriction*.

Let A a commutative \mathbb{C} -algebra, and Δ and D two \mathbb{C} -derivations of A satisfying

$$\Delta D - D\Delta = D.$$

The Connes-Moscovici deformation on A associated to (D, Δ) is the sequence $(\text{CM}_n^{D, \Delta})_{n \geq 0}$ of bilinear maps $A \times A \rightarrow A$ defined for any $f, g \in A$ by

$$\text{CM}_n^{D, \Delta}(f, g) = \sum_{r=0}^n \frac{(-1)^r}{r!(n-r)!} D^r (2\Delta + r)^{(n-r)}(f) D^{n-r} (2\Delta + n - r)^{(r)}(g),$$

with convention $1 = \text{Id}_A$ and for any function $F: A \rightarrow A$ the Pochhammer notation:

$$F^{(0)} = 1 \quad \text{and} \quad F^{(m)} = F(F+1) \cdots (F+m-1) \quad \text{for any } m \geq 1.$$

Théorème 2.3. *Consider a commutative \mathbb{C} -algebra R and a subalgebra A of R . Let Δ and θ be two \mathbb{C} -derivations of R such that $\Delta\theta - \theta\Delta = \theta$. We assume that*

- (1) $\Delta(A) \subseteq A$ and $\theta(A) \subseteq A$;
- (2) there exists $h \in A$ such as $\Delta(h) = 2h$;
- (3) there exists $x \in R, x \notin A$ such that $\Delta(x) = x$ and $\theta(x) = -x^2 + h$.

Then, the derivation $D := \theta + 2x\Delta$ of R satisfies $\Delta D - D\Delta = D$ and the Connes-Moscovici deformation $(\text{CM}_n^{D, \Delta})_{n \geq 0}$ of R defines by restriction to A a formal deformation of A .

$$A = \mathcal{J}^{\leq 0, \infty} \subset \mathcal{J}^{\leq \infty} = R, \Delta(f) = \frac{k}{2}f, \theta = \frac{1}{4}(\text{Ob} - E_1 \partial_z), x = \frac{1}{4}e_2, h = -\frac{5}{16}e_4.$$

However, \mathcal{J} and $\mathcal{J} < \infty, 0 >$ are not stable by $([\cdot, \cdot]_n)_{n \in \mathbb{Z}_{\geq 0}}$.

2.4.2. *Rankin-Cohen brackets of quasimodular type.* Consider

$$d = \partial_\tau + \frac{1}{4} E_1 \partial_z = \frac{1}{4} \text{Ob} + \frac{1}{2} e_2 \Delta$$

and consider the sequence $(\llbracket \cdot, \cdot \rrbracket_n)_{n \geq 0}$ of applications from $\mathcal{J}^{\leq \infty} \times \mathcal{J}^{\leq \infty}$ to $\mathcal{J}^{\leq \infty}$ defined by bilinear extension of

$$\llbracket f, g \rrbracket_n = \sum_{r=0}^n (-1)^r \binom{k+n-1}{n-r} \binom{l+n-1}{r} d^r(f) d^{n-r}(g)$$

for all $f \in \mathcal{J}_k^{\leq \infty}$, $g \in \mathcal{J}_l^{\leq \infty}$.

Since Ob stabilises $\mathcal{J}^{\leq \infty, 0}$, then $\mathcal{J}^{\leq \infty}$ and $\mathcal{J}^{\leq \infty, 0}$ are stable by any linear combination of $d^r(f) d^{n-r}(g)$. Again, applying our general method we find that the particular choice of coefficients implies that the sequence we have built is a formal deformation of $\mathcal{J}^{\leq \infty}$ and $\mathcal{J}^{\leq \infty, 0}$.

Our extension-restriction method implies the more remarkable following statement : $(\llbracket \cdot, \cdot \rrbracket_n)_n$ is a formal deformation of \mathcal{J} .

2.4.3. The transvectant approach. Reference: [Olv99, DMR24]

Finally, to build a sequence of bilinear maps that stabilises again $\mathcal{J}^{\leq \infty, 0}$ but not trivially we use the notion of transvectant due to Cayley.

The r -th transvectant of $f, g \in C^\infty(\mathbb{C}^2)$ is

$$\{f, g\}_n : \begin{array}{ccc} \mathbb{C}^2 & \rightarrow & \mathbb{C} \\ (x, y) & \mapsto & \Omega^n(((x_1, y_1), (x_2, y_2)) \mapsto f(x_1, y_1)g(x_2, y_2))(x, y) \end{array}$$

where

$$\Omega = \det \begin{pmatrix} \partial/\partial x_1 & \partial/\partial y_1 \\ \partial/\partial x_2 & \partial/\partial y_2 \end{pmatrix}.$$

One can compute an explicit form:

$$\{f, g\}_n = \sum_{r=0}^n (-1)^r \binom{n}{r} \frac{\partial^n f}{\partial x^{n-r} \partial y^r} \frac{\partial^n g}{\partial x^r \partial y^{n-r}}$$

and that the sequence $(\frac{1}{n!} \{ \cdot, \cdot \}_n)_n$ is a formal deformation of $C^\infty(\mathbb{C}^2)$.

Two other properties are:

- (1) a recurrence formula (just the binomial theorem...):

$$\{f, g\}_{n+1} = \{\partial_x f, \partial_y g\}_n - \{\partial_y f, \partial_x g\}_n$$

that allows to compute recursively all the brackets one we have seen that the 0 bracket is the product

(2) the formal deformation property is equivalent to

$$\sum_{r=0}^n \binom{n}{r} \{\{f, g\}_r, h\}_{n-r} = \sum_{r=0}^n \binom{n}{r} \{f, \{g, h\}_r\}_{n-r}.$$

These two properties are our main tool to prove that $(\frac{1}{n!} \{ , \}_n)_n$ is indeed a formal deformation of $\mathcal{J}^{\leq \infty, 0}$.

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